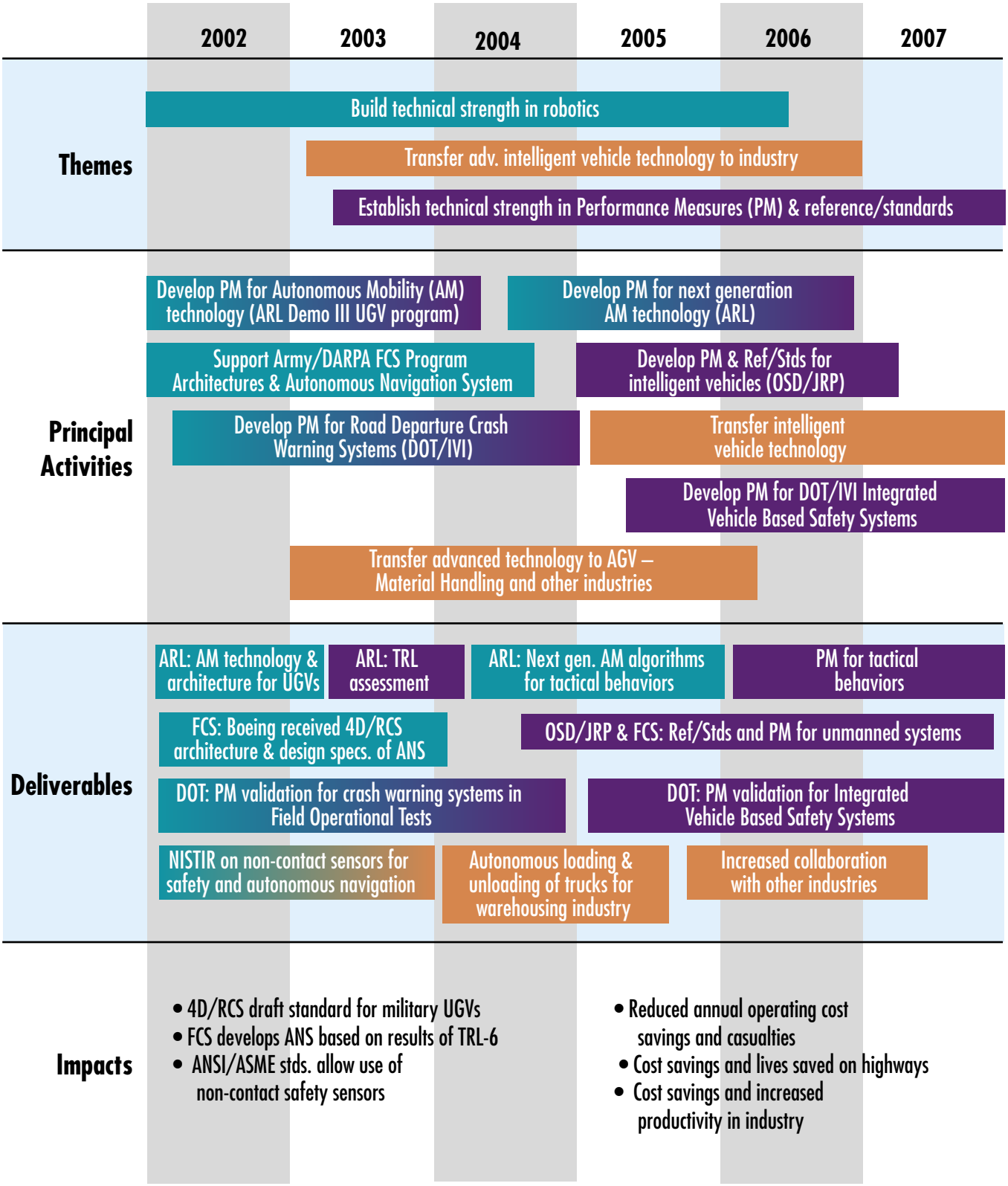Intelligent Control of Mobility Systems